

# *M illM in der*

# **AUDIO SIGNAL CONVERTER**

**IM-1**

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# **CATALOG NUMBERING SYSTEM**



- ENCLOSURE NEMA 4 MILD STEEL
	- NEMA 4X 304 STAINLESS STEEL
	- 20"H X 16"W X 7.5"D

INPUT - MILLPHONE

- OUTPUT ONE PER CHANNEL, EACH WITH AN INDIVIDUAL ZERO AND SPAN TO ALIGN RECORDER TRACE OR TO SUIT SPECIAL CALIBRATION
	- 4-20 MA INTO 750 OHMS MAX.
	- ALL NEGATIVE TERMINALS ARE ON A COMMON BUS

# **INSTALLATION**

#### **MODULE RACK**

The Module Rack should be mounted in an area that is clean, dry, vibration free, within the equipment 's ambient temperature range and non -corrosive to the electronics or the enclosure if supplied. The enclosure door should swing fully, allowing access for wiring and calibration.

#### DO NOT MOUNT THE MODULE RACK IN DIRECT SUNLIGHT

Refer to figure 1 for mounting dimensions and remove the Module Rack from the enclosure when drilling for conduit or cable entrance.

#### MILLPHONE

The millphone location on the mill shell is extremely critical as there may be only a small specific area where the sound signal is actually inversely proportional to the mill load. Some locations will have sound signal reversals, that is, for a further decrease in actual load the mill will start to become quieter.

Therefore, the mounting bracket s must allow for a large variation in microphone location so that the final location can be determined during start-up of the control system. Refer to figure 2 for mechanical dimensions and figure 3 for the area of the mill shell that must fall within the adjustment range of the microphone.

#### INTERCONNECTION and CABLING

#### ALL WIRING MUST BE DONE IN CONJUNCTION WITH APPROVED CONDUIT, BOXES AND FITTINGS AND TO PROCEDURES IN ACCORDANCE WITH ALL GOVERNING REGULATIONS.

The Module Rack and millphone (s) should b e interconnected per figure 4. The cabling should be a two wire twisted shielded pair from the microphone to the Module Rack. Use Belden 8760 or equivalent to a maximum run of 1,000 feet.

The mA output signal cabling can also be Belden 8760, to a maximu m run of 2000 feet.

Cabling should be run in separate conduits or in instrument cable trays per standard instrumentation practices. The microphone signals are low -level millivolt A.C. and deserve the consideration these types of signal levels require.

#### **Millphone locations are identified in the application bulletins in the back of this manual.**

# **OPERATION**

#### **APPLICATIONS**

The MillMinder is a mill load level sensing system used to monitor the sound (noise) emanating from a grinding mill. The millphone assembl y placed below the point of impact between the mill charge and the mill shell detects the predominantly audible frequencies. The millphone / sound sensor transmits its signal to an amplifier / converter where the signal at a selected frequency is amplified and converted to an analog mA output signal.

#### **CIRCUIT DESCRIPTION**

The MillMinder contains the following cards



#### MODULE RACK, MR-50

The MR-50 is supplied with 115 VAC (or optional 230 VAC) power supply. The supply line is wired into terminal block 6TB. There is a set of fused (5A Slo -Blo) auxiliary supply terminals provided. An On / Off power switch is supplied for the MR-50 but the au xiliary supply is not switched. A  $\frac{1}{4}$  AMP Slo -Blo (1/8 Amp for 230 VAC units) fuse protects the supply line and a surge suppressor is used to protect the circuitry from high surges in the supply. The transformers and large filter capacitors for the power supply are mounted on the MR-50 Module Rack.

#### VOLTAGE REGULATOR, VR-50

The VR-50 consists of three power supplies for the system. The card is plugged into 7ECN on the MR-50 Module Rack.

There is a  $+5V$  bus, with D COMMON, for the digital circuitry, a  $+24V$  bus, with P COMMON, for the relay driver circuits, and  $a + 15V$  and  $-15V$  bus, with A COMMON for the analog circuitry. The three commons are connected together on the VR -50 card, but are to be wired as separate COMMON busses at the terminal block 7TB on the MR-50.

The four LED's indicate when the power supply is ON. If the supply is less than rated, the LED will be dimmer than normal.

#### METER CARD, MC-50

The MC-50 is a 0 to  $+10$  VDC meter which is used during setup and calibration.

The MC-50 consists of a full wave precision rectifier to assure that there will be a positive voltage to the meter regardless of the polarity of the input signal.

The input signal connected at test point TP2 (Red) is fed through a buffer, IC1-c. The signal is applied directly to an inverting amplifier, IC1 -a, and through a half wave rectifier, IC1-b.

If the input is a negative voltage the voltage at the anode of D1 will be zero. Therefore, the output of IC1-a is the inverted signal.

If the input is positive voltage the output of IC1-b will be the inverted input signal. This is summed with the input signal. The output of IC1.a is the input signal plus twice the inverted input signal.

The signal is available at the test point TP1 (Yellow) for connection to an auxiliary meter.

The COMMON test point TP3 (Green), is used when measuring a signal from equipment other than the MR-50 and for use with an auxiliary meter.

The LED signifies a negative voltage input.

#### SONIC SENSOR CARD, SS-50

The SS-50 is an input card for t he millphone signal. The cards are plugged into edge connectors 1ECN to 5ECN on the MR -50 Module Rack, one per channel (millphone). The SS -50 consists of a signal conditioner, limit circuitry and a voltage to current converter.

The signal conditioner consists of a two-stage amplifier with fine and coarse gain control, an active filter with adjustable center frequency dependent upon the type of mill being controlled (refer to Page 8 for R  $_{A}$  and R<sub>B</sub> values for a specific frequency), and a full wave precision rectifier with an offset and gain control.

The two stage amplifier consists of IC1 and IC2 with coarse gain control SW1, and fine gain control (P1) GAIN A. R24A is used as a load resistor for the microphone's transformer secondary. The gain ranges from 0.25 to 54.

The signal is then processed through an active band pass filter, IC3 to amplify the desired frequency. The center frequency of the filter is selected with the

FREQUENCY switch, SW2. Position 1 is 3.3 KHz, position 2 is for 1 KHz, and position 3 is for a custom frequency.

The full wave precision rectifier consists of a half wave rectifier (IC4  $-$ a) and in inverting amplified (IC4-b).

The voltage at the anode of D2 will be zero when the signal is negative. When the input is positive the voltage will be the inverted input.

Therefore, the output of IC4-b will always be positive when the OFFSET voltage is zero. The output of IC4 -b can be doubled with GAIN B. This signal can be seen at the Blue test point TP3, (V in). This voltage varies fro m 0 to 10 VDC for an input signal level of 1 to 100%.

'V in' is connected to an amplifier whose output is offset by a voltage of  $-10V$ . This signal is a 0 to 10 VDC signal proportional to the load of the mill and is available at the Yellow test point TP2, (V out).

'V out ' is converted to an analog mA output signal with ZERO and SPAN adjustments. The circuitry will maintain a stable current output signal referenced to COMMON throughout the rated load.

The circuitry is basically a closed loop regulating f eedback system. 'V out', which has SPAN adjustment, is summed at the input IC6 -a with the feedback signal, which is proportional to the current flow. IC6 -a acts as a very high gain comparator. There is an offset current adjustment via the ZERO potentiom eter at this summing junction. Any error between the two signals will cause the output current flowing through sensing resistor R65 to vary in a direction to reduce the error to zero. IC6-b functions as a unity gain inverter driving the level shifting ci rcuitry consisting of Q1 and R64 which drives the current output transistor Q2.

It is important to note that the output voltage developed across the current sensing resistor, R65, will float with respect to COMMON, a varying amount dependent on the extern ally connected op amp with a very high common mode rejection ratio, and ensures that the floating current signal is sensed accurately.

In order to achieve the required high common mode rejected, it is necessary to observe the design requirement that the r atio of R63 to R73 is the same ratio of R77 to R75. The requirement is achieved by using 1% resistors and inserting a small trim -pot, P9, which may be adjusted to achieve the required exact ratio. P9 is a sealed factory adjustment.

The output of IC6 -c is connected to a voltage follower, IC6 -d, to give a voltage signal representing the current output with ZERO and SPAN adjustments.

# **CALIBRATION**

#### SS – 50 Set-up Procedure

The following setting are preset at the factory:





#### Dynamic Adjustment to First Compartment (With mill running at normal levels)

- 1.1 Connect a jumper wire between V IN test point TP-3 (Blue) on the SS-50 card to the SIGNAL test point TP-2 (Red) on the MC-50 meter card.
- 1.2 Adjust coarse GAIN switch (SW1) until the meter card reads between 1 and 5 VDC.
- 1.3 Adjust fine GAIN A (P1) potentiometer clockwise until meter card reads 5 VDC.
- 1.4 Connect the jumper from TP-2 (Red) on the meter card to V OUT test point TP-2 (Yellow) on the SS-50 card. The reading should be 5 VDC +/- 0.5.
- 1.5 Adjust the RATE potentiometer (P5) on the SS-50 card until the meter reading has about a 0.5 to 0.75 volt short term bounce.
- 1.6 ZERO (P7) and SPAN (P8) have been factory set to provide a 4-20 mA output with a V OUT change of 0 to 10 VDC.

#### Dynamic Adjustment to Second Compartment

- 2.1 Connect a jumper wire between V IN test point TP-3 (Blue) on the SS-50 card to the SIGNAL test point TP-2 (Red) on the MC-50 meter card.
- 2.2 Adjust coarse GAIN switch (SW1) until the meter card reads between 1 and 5 VDC.<br>2.3 Adjust fine GAIN A (P1) potentiometer clockwise until meter card reads 5 VDC.
- 2.3 Adjust fine GAIN A (P1) potentiometer clockwise until meter card reads 5 VDC.<br>2.4 Adjust GAIN B (P3) potentiometer clockwise 10 turns. The meter reading shoul
- Adjust GAIN B (P3) potentiometer clockwise 10 turns. The meter reading should now be less than 5 VDC.
- 2.5 Adjust the OFFSET (P2) potentiometer until the meter card reading is 5V.<br>2.6 Connect the jumper from TP-2 (Red) on the meter card to V OUT test poir
- 2.6 Connect the jumper from TP-2 (Red) on the meter card to V OUT test point TP-2 (Yellow) on the SS-50 card. The reading should be 5 VDC +/- 0.5.
- 2.7 Adjust the RATE potentiometer (P5) on the SS-50 card until the meter reading has about a 0.5 to 0.75 volt short term bounce.

#### Increasing Sound Sensitivity to Load Changes (When required)

The need for this adjustment will be determined during actual automatic start-up and automatic operation.

- 3.1 Follow steps 2.1 2.3
- 3.2 Instead of following step 2.4, turn GAIN B (P3) potentiometer clockwise 5 turns.<br>3.3 Observe sound change results.
- Observe sound change results.
- 3.4 If sound changes are deemed not to be significant enough, increase GAIN B two turns at a time until results are satisfactory.
- 3.5 Complete steps 2.5 2.7

#### 4-20 mA Trace Relocation

There are occasions when the trace created by the 4-20 mA output on a recorder may not be located correctly or interferes with another trace on a multi-trace recorder. The 4-20 mA potentiometers may be adjusted to match the recorder trace.

- 4.1 Jumper terminals 1 and 2 on the TB 1 through 5 associated with the correct SS-50 card.<br>4.2 This will cause the V OUT signal to go to 10 VDC (or close to it).
- 4.2 This will cause the V OUT signal to go to 10 VDC (or close to it).<br>4.3 Adiust the SPAN (P8) until the desired output current or recorder
- Adjust the SPAN (P8) until the desired output current or recorder trace position is achieved.

#### Fine Tuning from the Frequency Chart

Center frequencies may be adjusted by bridging various value resistors across RA and RB plug points. Refer to the following chart for correct values:



Appendix A

Drawings















Appendix B

Application Bulletins

#### Cement Finish Mill – Dual Compartment

Microphone Location:

The Microphone on the first compartment in this instance is the most critical and important element. This microphone should be placed about 1/3 of the way from the feed end. If it is too far forward, the sound will not be responsive to recirculating load changes. If it is too far back, the sound will not be responsive to new feed changes. The discharge microphone should be mounted approximately 1/3 of the way from the discharge end. However, if problems of plugging with the discharge grate occur, move this microphone to within three bolt rows of the discharge end.



Sonic Sensor Amplifier Frequency: 3300 Hz

2500 Hz



Cement, Rock (Wet and Dry) Mill – Single Compartment

Microphone Location:

On this type of mill, the microphone position is not extremely critical, however, experience indicates that the microphone should be mounted just forward of the center of the mill. Mounting between 1/3 and 1/2 from the feed end should easily prove this. In general, with high re-circulating loads, move the microphone towards the feed end and with low re-circulating loads, move the microphone towards the discharge end.





#### Cement Raw Mill (Wet) – Dual Compartment

Microphone Location:

On these mills, the feed end microphone should be placed fairly close to the discharge end of the primary compartment. This is required because of "water" noise signals caused when the surface area presented by the coarse feed to absorb the water is very small. As a result the water flushes through the area before the rock is broken down giving erroneous signals. The feed end microphone is primarily used to prevent plugging of this discharge grate into the second or succeeding compartments. The microphone on the discharge compartment should be located between 1/3 and 1/2 of the compartment length from the feed end. Here a good homogeneous mixture of slurry should exist and a normal sound signal should result if density is held constant.





#### Aerofall (Sag) Mill – Single Compartment

Microphone Location:

Microphone should be mounted at the 6 o' clock position with the midpoint along the length of the grinding area. Wet mills may have a lifting chamber which will add to mill length. However, do not include this section when centering microphone. Place microphone as close as possible to the mill shell. Beware of flanges which are used to bolt the mill shell together. If ambient noise level is high, shield microphone.



Sonic Sensor Amplifier Frequency: 3300 Hz as supplied

2100 Hz best dry/wet 1750 Hz wet, small feed



#### Cascade Type Mill – Single Compartment

Microphone Location:

The Microphone on these types of mills should be placed below the toe of the charge. The exact position being defined as a result of how much the mill charge volume changes. The microphone must be at least 0.5 hours below the lowest charge "TOE". Trial and error will be the final judge as to whether the microphone should be lower.







#### Rod Mill – Single Compartment

Microphone Location:

The Microphone on these types of mills should be placed roughly 1/3 of the way from the discharge end. However, trial and error selection should also include observation at 1 row of bolts either side of the 1/3 position. The microphone should be mounted well down and not higher than 5 o'clock, with 5:15 to 5:30 being the preferable location, especially if rod mill speeds are around 75% critical.





#### Regrind Mill – Single Compartment

Microphone Location:

The Microphone should be placed approximately ½ way along the mill length slightly toward the discharge end. The microphone should be placed between 4:30 and 5:45 depending on the mill speed and charge. Generally, approximately 5:15 should be the optimal position.







Coal Mill, Air Swept, Single Discharge – Dual Compartment

Microphone Location:

The Microphone should be placed approximately in the center of the first grinding compartment. The discharge microphone should be located about 1/3 of the way from the mill discharge.



Sonic Sensor Amplifier Frequency: 3300 Hz



Center Discharge, Airswept – Dual Compartment

Microphone Location:

The Microphone on the feed end should be mounted approximately 1/3 to 1/2 distance from the feed end of the primary grinding compartment. the microphone on the secondary grinding compartment should be located about the center of that compartment.





Airswept – Single Compartment

Microphone Location:

The Microphone should be located about 1/3 of the distance from the feed end of the mill.



